

A Decidable Spatial Logic With Cone-shaped Cardinal Directions

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CSL'09

Shortly

This talk is about **deciding satisfiability** of formulas from a suitable **modal logic** under interpretation over **labeled rational planes** $\mathcal{L} : \mathbb{Q} \times \mathbb{Q} \rightarrow \mathcal{P}(A)$.

An example – Compass Logic (Venema '90)

Formulas of **Compass Logic** are defined by the following grammar:

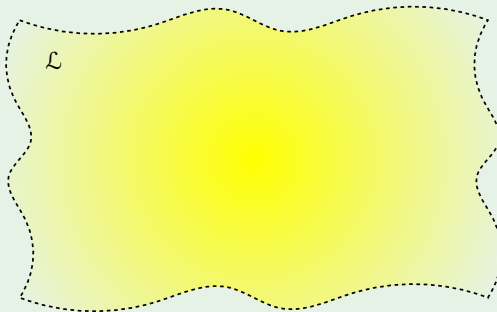
$$\begin{array}{l}
 \varphi \quad := \quad a \quad | \quad \neg\varphi \quad | \quad \varphi \vee \varphi \quad | \quad \varphi \wedge \varphi \quad | \\
 \quad \quad \diamondrightarrow\varphi \quad | \quad \diamondup\varphi \quad | \quad \diamondleft\varphi \quad | \quad \diamonddown\varphi \quad | \\
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Formulas are evaluated over *labeled points* of the rational planes...

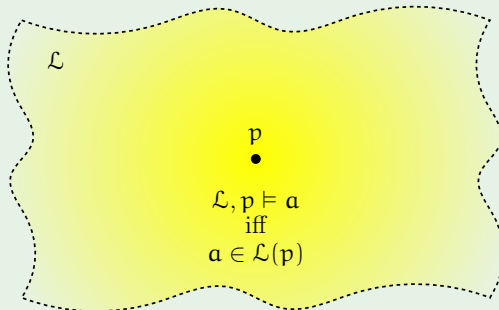


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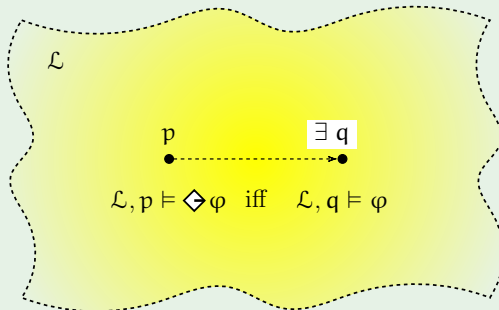


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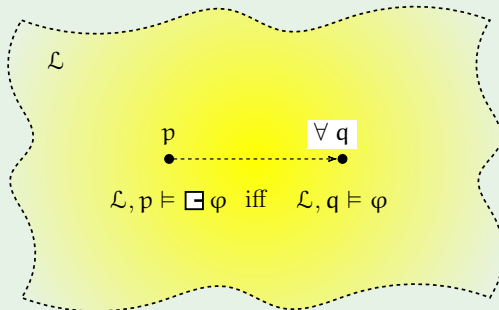


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Satisfiability problem

The **satisfiability problem** consists of deciding, given a formula φ , whether there exist *a labeled structure* \mathcal{L} and *a point* p such that

$$\mathcal{L}, p \models \varphi.$$

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Unfortunately...

Theorem (Marx and Reynolds '99)

The satisfiability problem for Compass Logic is **undecidable**.

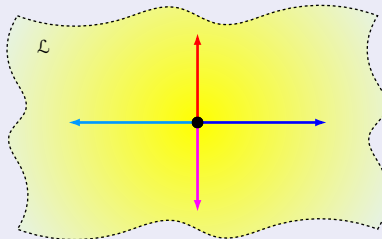
(one can encode an infinite tiling using \blacktriangleleft , \blacktriangleright , \blacktriangle , \blacktriangledown ...)

Decidability may be recovered by **weakening** Compass Logic...

Cone Logic as a weakening of Compass logic

Instead of having modalities for the *positive/negative* x -/ y -axes...

existential
modalities:



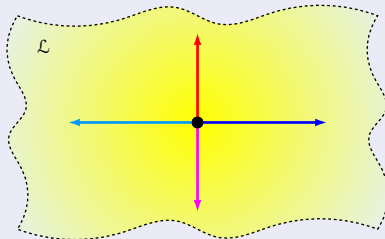
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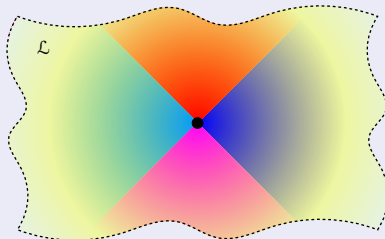
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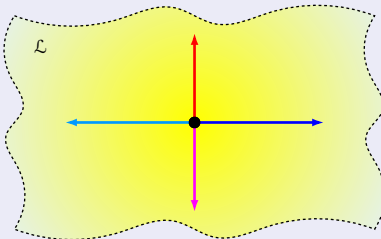
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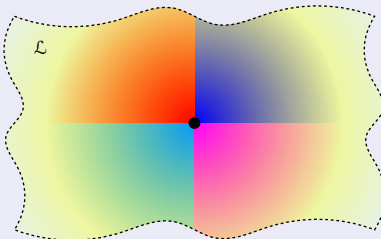
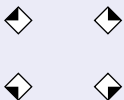


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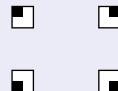


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Cone Logic formulas

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 \quad \quad \blacksquare\varphi \quad | \quad \square\varphi \quad | \quad \blacksquare\varphi \quad | \quad \square\varphi \quad |
 \end{array}$$

The modal operators \blacktriangleleft , \blacktriangleright , \blacktriangledown , \blacktriangleup , \blacksquare , \square , \blacksquare , \square quantify over points of the four **open** quadrants, e.g.,

$$\text{Dom}(\blacktriangleleft) = \{q = (x, y) : x > 0, y > 0\}.$$

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The modal operators \blacktriangleleft^+ , \blacktriangleright^+ , \blacktriangledown^+ , \blacktriangleup^+ , \blacksquare^+ , \square^+ , \blacksquare^+ , \square^+ quantify over points of the four **semi-closed** quadrants, e.g.,

$$\text{Dom}(\blacktriangleleft^+) = \{q = (x, y) : x \geq 0, y \geq 0\} \setminus \{(0, 0)\}.$$

Cone Logic makes it easy to express spatial relationships based on (approximate) cardinal directions...

Example 1

“For every pair of points p and q labeled, respectively, by a and b , q is to the North-East of p .”

is expressed by the Cone Logic formula

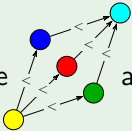
$$\varphi = \blacksquare (a \rightarrow \square \neg b \wedge \blacksquare \neg b \wedge \square \neg b)$$

where \blacksquare is a shorthand for $\square \square$

(equivalent to “for every point of the plane”).

...and it can also express also interesting properties of the plane!

Example 2

Let A be the lattice  and consider the Hintikka-like formula

$$\varphi_A = \blacksquare \bigvee_{a \in A} a \wedge \blacksquare \bigwedge_{a \neq b} \neg(a \wedge b)$$

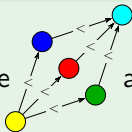
$$\wedge \blacksquare \bigwedge_{a \in A} \left(a \rightarrow \bigwedge_{b \leq a} \blacklozenge b \wedge \bigwedge_{b \geq a} \blacktriangleright b \wedge \blacksquare \bigvee_{b \leq a} b \wedge \blacksquare \bigvee_{b \geq a} b \right)$$

\mathcal{L}



Example 2

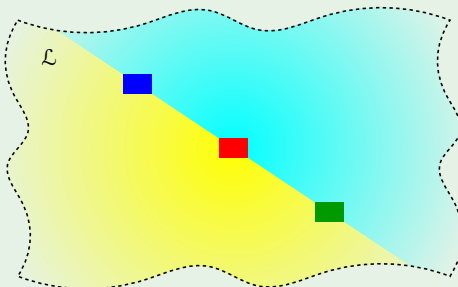
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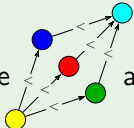
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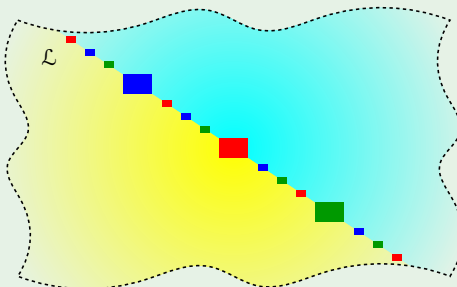


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To solve the satisfiability problem for Cone Logic, we consider *portions* of the rational plane:

Stripe

A **stripe** of a labeled rational plane $\mathcal{L} : \mathbb{Q} \times \mathbb{Q} \rightarrow \mathbb{A}$ is the restriction $\mathcal{L}_{[x_0, x_1]}$ of \mathcal{L} to a region of the form $[x_0, x_1] \times \mathbb{Q}$.

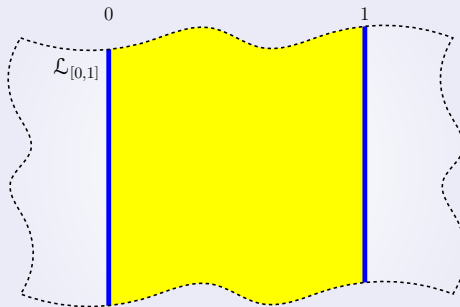
Fact

Any Cone Logic formula φ can be translated into a formula $\varphi_{[x_0, x_1]}$ in such a way that, for every labeled rational plane \mathcal{L} ,

$$\begin{array}{ccc} \exists p \in \mathbb{Q} \times \mathbb{Q}. & \text{iff} & \exists p \in [x_0, x_1] \times \mathbb{Q}. \\ \mathcal{L}, p \models \varphi & & \mathcal{L}_{[x_0, x_1]}, p \models \varphi_{[x_0, x_1]}. \end{array}$$

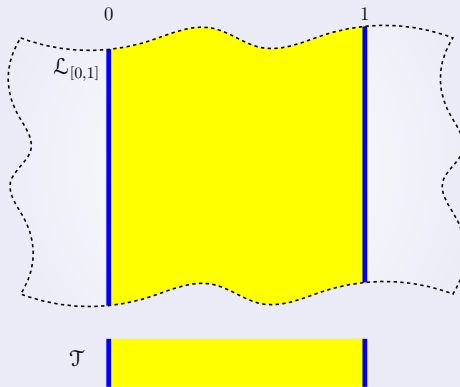
\Rightarrow We can restrict our attention to **satisfiability over a stripe** $\mathcal{L}_{[0,1]}$ (and we forget, for the moment, the operators \blacklozenge^+ , \blacktriangleleft^+ , ...).

Decompositions of stripes

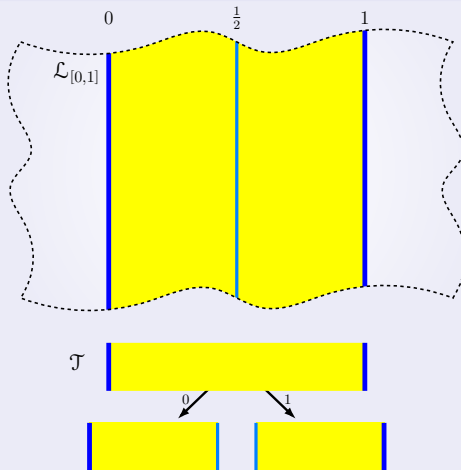


By exploiting isomorphism between the orders over $[0, 1]$ and over $\left\{ \frac{i}{2^n} : n \in \mathbb{N}, 0 \leq i \leq 2^n \right\}$, we decompose the stripe $\mathcal{L}_{[0,1]}$ into a **tree structure** $\mathcal{T} \dots$

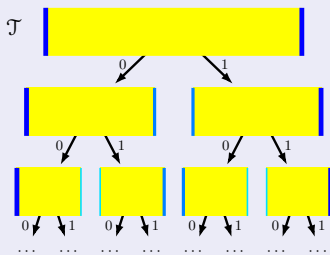
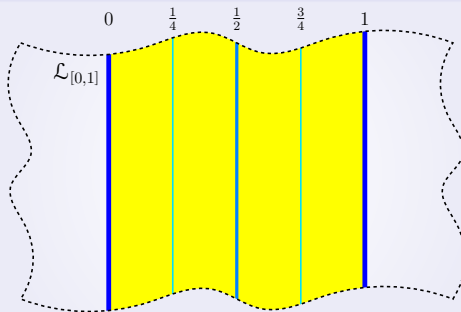
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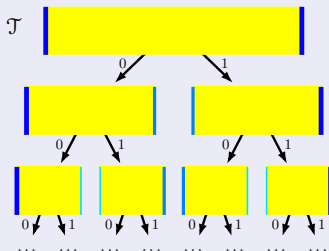


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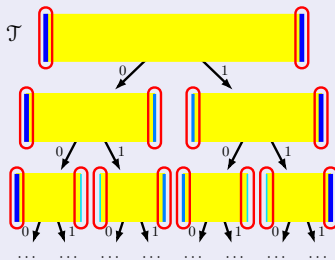
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Finite abstractions of stripes

Given a (sub-)stripe $\mathcal{L}_{[x_0, x_1]}$, we define an equivalence \approx over \mathbb{Q} such that $y \approx y'$ iff, for all formulas α (of bounded complexity),

$$\begin{array}{ccc}
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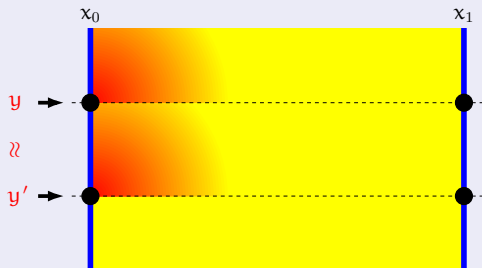
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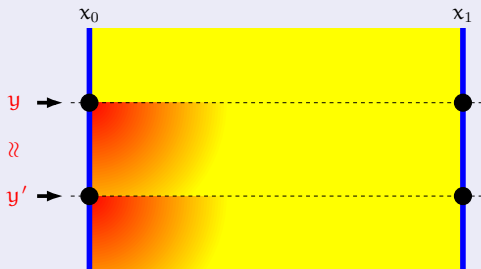
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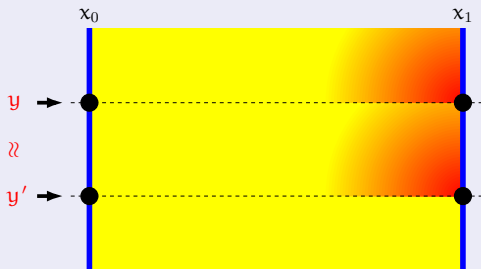
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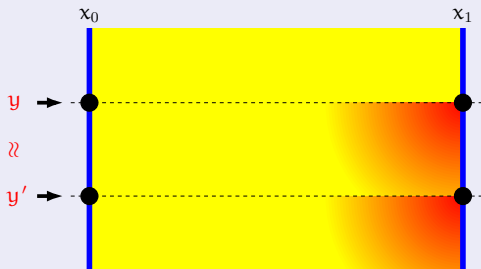
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Since the equivalence relation \approx has *finite index*, we have that

Proposition (a tree pseudo-model property)

Any given stripe $\mathcal{L}_{[0,1]}$ can be represented by means of a suitable *infinite binary tree* \mathcal{T} whose vertices are labeled over a finite alphabet (we call the structure \mathcal{T} a **tree decomposition** of $\mathcal{L}_{[0,1]}$).

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...However, tree decompositions must be **properly constrained** so that they correctly represents some concrete stripes.

Examples of constraints on a tree decomposition

- For every pair of *sibling* vertices $v = [x_0, x_1]$ and $v' = [x'_0, x'_1]$ in \mathcal{T} , the labeling of the right border of v has to *match* with the labeling of the left border of v' (in such a way, we can assume $x_1 = x'_0$),
- There is *no infinite path* π in \mathcal{T} such that, for every vertex $v \in \pi$, $\blacktriangleleft \alpha$ appears on the *left border* of v and neither $\blacktriangleright \alpha$ nor α appear on the *right border* of v .

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Constrained tree decompositions can be defined in a **fragment of CTL**, which we denote **CTL⁻**.

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Theorem 2 (deciding satisfiability of CTL⁻)

The satisfiability problem for CTL⁻ (\Rightarrow Cone Logic) is in **PSPACE**.

Proof idea

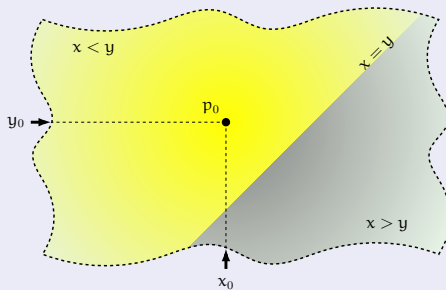
CTL⁻ formulas are *conjunctions* of the following basic formulas:

- 1 $\mathbf{AG}(left \vee right)$, $\mathbf{AG}\neg(left \wedge right)$, $\mathbf{AG}(\mathbf{EX}left \wedge \mathbf{EX}right)$
- 2 $\mathbf{AG}(\alpha)$, $\mathbf{AG}(\alpha \rightarrow \mathbf{AF}\alpha')$,
where α, α' contains only positive occurrences of the modal operator **AX** and no other operators.

\Rightarrow Checking satisfiability of these formulas amounts at deciding **universality of Büchi automata**.

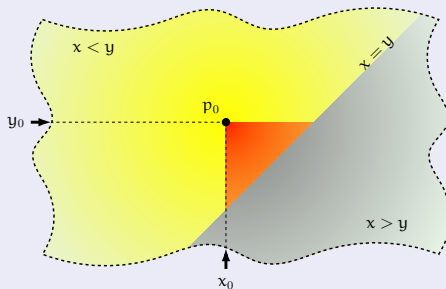
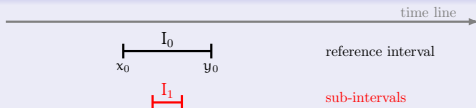
There is a natural correspondence between **intervals** $I = [x, y]$, with $x < y$, and **points** $p = (x, y)$ of the rational plane...

Spatial interpretation of intervals and their relationships



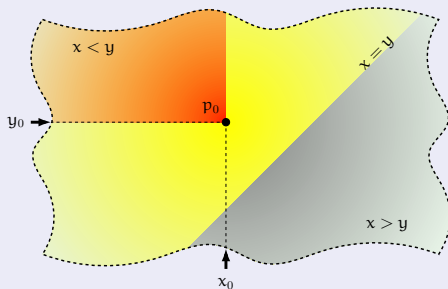
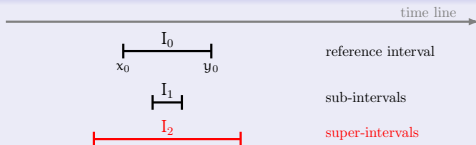
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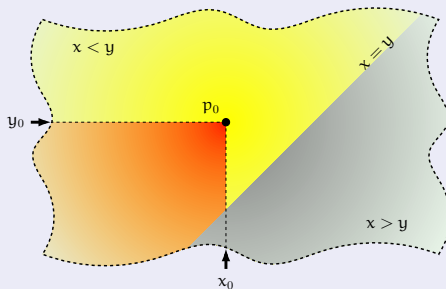
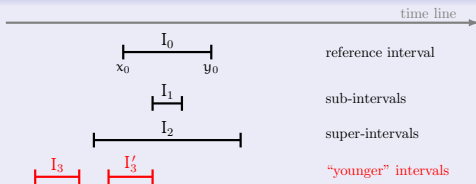
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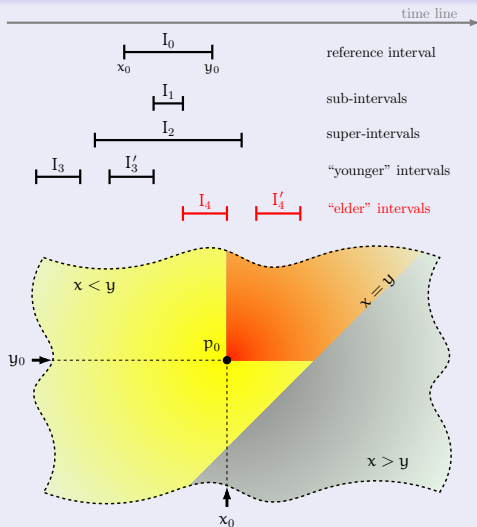
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Cone Interval Logic

We can introduce a new **interval temporal logic** by means of the following grammar:

$$\begin{array}{l} \varphi := \quad \alpha \quad | \quad \neg\varphi \quad | \quad \varphi \vee \varphi \quad | \quad \varphi \wedge \varphi \quad | \\ \quad \langle sub \rangle \varphi \quad | \quad \langle super \rangle \varphi \quad | \quad \langle younger \rangle \varphi \quad | \quad \langle elder \rangle \varphi \quad | \\ \quad [sub] \varphi \quad | \quad [super] \varphi \quad | \quad [younger] \varphi \quad | \quad [elder] \varphi. \end{array}$$

Formulas are evaluated over *labeled intervals* of the rational line.

Note: *sub* and *super* correspond to Allen's interval relations D and \bar{D} , while *younger* and *elder* are unions of other Allen's interval relations (e.g., $elder = O \cup E \cup A \cup L$).

Moreover, Cone Interval Logic generalizes previous interval temporal logics (cf. [Bresolin, Goranko, Montanari, Sala '08]).

Fact 1

The modal operators $\langle sub \rangle$, $\langle super \rangle$, $\langle younger \rangle$, $\langle elder \rangle$, ... are **definable** by means of the modal operators \blacklozenge , \blacktriangleleft , \blacktriangleright , \blacklozenge , ...

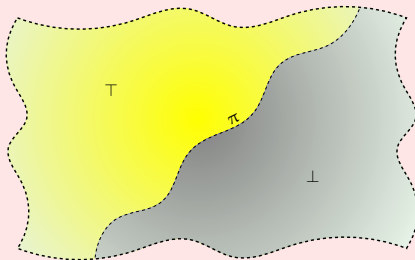
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Fact 2

The “yellow region” of valid intervals (i.e., $\{p = (x, y) : x < y\}$) is **definable** (up to “deformations”) inside the rational plane:

$$\begin{aligned} & \blacksquare(T \vee \perp \vee \pi) \wedge \blacksquare(\neg T \vee \neg \perp) \wedge \blacksquare(\neg T \vee \neg \pi) \wedge \blacksquare(\neg \perp \vee \neg \pi) \wedge \\ & \blacksquare(T \rightarrow \blacklozenge T \wedge \blacksquare T) \wedge \blacksquare(\perp \rightarrow \blacklozenge \perp \wedge \blacksquare \perp) \wedge \\ & \blacksquare(\pi \rightarrow \blacksquare^+ T \wedge \blacksquare^+ \perp) \wedge \blacksquare(\blacklozenge \pi \wedge \blacklozenge \pi \rightarrow \pi \vee \blacklozenge \pi \vee \blacklozenge \pi). \end{aligned}$$



From previous results we have:

Corollary (decidability of Cone Interval Logic)

The satisfiability problem for Cone Interval Logic is in **PSPACE**.

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The satisfiability problem for Cone Interval Logic is in **PSPACE**.

Theorem (Shapirovsy and Shehtman '03)

The satisfiability problem for the fragment of Cone Interval Logic that comprised only the modal operators $\langle sub \rangle$ and $[sub]$ is **PSPACE-hard**.

⇒ This also implies that the decision procedure for satisfiability of Cone Logic formulas is **optimal**.

Summary

In conclusion, Cone Logic

- is a **weakening** of Venema's Compass Logic,
- has a **PSPACE-complete** satisfiability problem,
- subsumes interesting **interval temporal logics**.

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- spaces with **more than 2 dimensions** (e.g., \mathbb{Q}^3),
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Thank
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